

Variability and Predictability of Large-Scale Wind Energy in the Netherlands

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1. Introduction

This chapter presents in a national context energy balancing requirements due to the variability and the limited predictability of wind energy in the thermal energy system of the Netherlands. In addition options to reduce these requirements are discussed. To this end 7.8 GW of wind power capacity in a system with 35 GW of total capacity is considered. The balancing requirements due to the cross-border flow of wind energy (export of domestic wind energy or import of foreign wind energy) however are not covered as these require an international context (ETSO, 2008). In addition the potential benefits of an intra-day market are not explored.

This chapter is organized as follows. First, section 2 presents various scenarios for wind and other energy capacity in the Netherlands, and introduces the structure of the Dutch electricity market. Next, section 3 gives a short overview of studies which addressed balancing energy reduction options in the contexts of the electricity markets in Denmark, Germany and Spain. Section 4 continues with the modeling of wind variability and wind predictability and its relevance to wind energy integration. Sections 5 and 6 then present the balancing energy requirements due to wind variability and limited wind predictability. Subsequently, section 7 discusses options to reduce the extra balancing energy requirements, which options include short-term forecast updates, aggregation, pumped storage, compressed air energy storage, fast start-up units, inverse offshore pump accumulation system, and wind farm shut-down strategies. Finally, section 8 summarizes the results.

2. Energy scenarios and market structure

2.1 Synopsis

In order to study balancing energy requirements in the future in the Netherlands, various energy scenarios were developed. These are presented in section 2.2, with attention for wind energy production capacity (paragraph 2.2.1), total electricity production capacity (paragraph 2.2.2), and flexibility of production (paragraph 2.2.3). The future structure of the Dutch electricity market is presented in section 2.3. The material in this section has been published in greater detail in de Boer et al., 2007; Gibescu et al., 2008b; and Gibescu et al., 2009.

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2.2 Energy scenarios

2.2.1 Wind energy capacity

Offshore wind energy growth scenarios were developed that are consistent with the renewable policy goals in the Netherlands over the period up to the year 2020. Based on these rough estimates, on the onshore wind farm placement in the year 2006, and on the pending applications for environmental permits for offshore wind farms, the most likely locations and installed capacities were chosen for the years 2010, 2015 and 2020. In addition, three offshore wind energy scenarios were created: Low, Basic and Advanced. Only one scenario was created for onshore wind installed capacity. The scenarios are summarized in table 1.

	Year		
	2010	2015	2020
Low Offshore	720	2010	3800
Basic Offshore	1180	3110	6030
Advanced Offshore	1520	4110	8000
Onshore	1750	1800	1800

Table 1. Scenarios for offshore and onshore wind capacity in MW in the Netherlands

The aim of the Dutch government (from the 2004 policy) was to have 20% of demand served with help of renewable energy in the year 2020. The scenario Advanced will cover this completely with wind energy (given capacity factors of 25% and 37% respectively for onshore and offshore). Since this is an optimistic view of wind energy growth, the Basic scenario is employed in this study.

The offshore locations of wind farms for the scenario Basic Offshore 2020 were derived from the requests for permits for wind farms in the North Sea as filed by early 2006.

2.2.2 Total electricity capacity

Scenarios for the total electricity capacity in the Netherlands were developed by considering the total production plant in the year 2005, and estimating the retirement and addition of plant by the years 2010-2015-2020. The resulting total capacity break-up for the year 2020 is shown in table 2.

Production in the Netherlands for several scenarios						
Type of power production	2005	2020				
	KEMA database	basic scenario	gas scenario	coal scenario	high growth scenario	low growth scenario
	MW	MW	MW	MW	MW	MW
Gas motor	1.450	1.950	1.950	1.950	2.260	1.680
Gas turbine	890	1.200	1.200	1.200	1.390	1.040
STAG of Combi	11.690	17.470	18.920	15.570	19.950	15.310
Conventional: boiler + ST (gas)	2.100	360	360	360	360	360
Conventional: boiler + ST (coal)	4.180	5.630	4.180	7.530	6.510	4.850
Nuclear	450	450	450	450	450	450
Waste and biomass	390	520	520	520	610	450
Wind	390	7.800	7.800	7.800	10.400	4.800
Total production	21.540	35.380	35.380	35.380	41.930	28.940

Table 2. Installed power in the Netherlands for several growth scenarios in 2020

As to the conventional production, on basis of the current practice, it is assumed that power plants can operate at 150% in respect to the original design. Their capacity is expected to decrease from 21 GW in the year 2005 to 9 GW in the year 2020. In addition, it is expected that most of the coal fired power plants and gas-fired combined cycle plants are still operating in the year 2020.

As to new production capacity five scenarios - each covering the years 2010–2015–2020 - were set up: basic, gas, coal, high growth, and low growth. The following parameters were considered: economic growth (respectively 1, 2 and 3% per year), fuel mix (basic scenario with current gas-to-coal ratio 1.0:3.5, a gas-and-coal reign scenario), and intensity of wind energy (see section 2.2.1).

In the basic scenario the control capabilities will be dominated the Combined Heat and Power (CHP) plants because the major growth of the capacity will most probably come from these plant. Power plants build after the year 2000 have better control capabilities: ~ 8% of nominal power per minute for gas, and ~3%/min for coal. The range of power change capability for CHP plants is 50% or more.

In the other scenarios the control capabilities differ slightly. For the coal scenario the rate of power change capabilities will be somewhat lower and for the gas scenario it will slightly higher.

2.2.3 Flexibility of production

Flexibility of production is required in order to follow the expected wind power variations, and to compensate unexpected wind power variations. This warrants a certain margin and rate of change capability, primary for the Programme Responsible Parties (PRPs) and secondly for the Transmission System Operator (TSO). The flexibility of production is defined in terms of: rate of change of the total capacity, amount of regulating (i.e. spinning) power and reserve power, rate of change of the spinning reserve units, and start time of the remaining units that are not delivering power during the load following cycle. Most of these terms depend on the operating point in the load following cycle and on the types of power units operating in that operating point.

A maximal ramping capability of $8\%P_{nom}/min$ is expected for gas-fired units and 3% for coal-fired units. In the year 2020 the morning shoulder (i.e. the difference between off-peak and peak load) is expected to cover approximately 10 GW with a maximal required ramp rate of 60 MW/min. The gas fired power units are expected to carry this ramping load. This implies that a minimum of 10 GW of gas-fired units have to be spinning. If they have an average rate of change of 4%/min, then 400 MW/min can become available. This is enough to handle the expected variability due to load.

2.3 Structure of the electricity market

In the Netherlands wind power has been fully integrated in the day-ahead and imbalance market structures since the year 2001, and this situation is not expected to change in the future. Market participants known as Programme Responsible Parties (PRPs), governing a portfolio consisting of both renewable and conventional energy resources, submit to the Transmission System Operator (TSO) balanced schedules for energy delivered to and absorbed from the system during a 15-minute interval known as Programme Time Unit (PTU). This arrangement provides some insulation from the full exposure to imbalance charges for the wind producer, as conventional units in the PRP's portfolio may act to correct energy programme deviations due to wind variability and limited predictability.

3. International experience

3.1 Overview

This section presents a short overview of studies on balancing energy reduction options in the contexts of the electricity markets in Denmark, Germany and Spain. Section 3.2 starts with a short survey of international experiences with instruments for balancing the variability and forecasting errors introduced by large-scale wind energy in a power system. The focus is on wind power forecast updates (paragraph 3.2.1), aggregation of wind power (paragraph 3.2.2), energy storage (paragraph 3.2.3), and wind farm control (paragraph 3.2.4). In addition, the design of balancing markets is addressed in subsection 3.3.

3.2 Technology

3.2.1 Wind power forecast updates

The quality of wind power forecasts significantly improves as the forecast horizon decreases (Lange and Focken, 2005). The state-of-the-art indicates that the capacity normalized root mean square error (cRMSE) may reach a minimum value of 2...3% for a lead time of 2 hours before delivery (Krauss et al., 2006). For example in Germany this significant improvement in the accuracy of wind power forecasts consequently allowed for a better commitment and dispatch of the other generation units (Krauss et al., 2006). By doing so, the reserves held for wind power were decreased and the resulting surplus power could be offered by the conventional units in for example the intra-day market. Also a more efficient use was made of the available ramping capabilities of different units.

3.2.2 Aggregation of wind power

Aggregation of wind power over a larger geographical area, apart from smoothing out variability, improves the quality of the forecast because of the partly uncorrelated character of the forecast errors (Lange & Focken, 2005; von Bremen et al., 2006). As a result, both the reserves held and the reserves actually applied in a control area are decreased. Balancing wind power across control areas is even more efficient (Krauss et al., 2006).

3.2.3 Energy storage

Due to the relatively high investment costs of large-scale energy storage technologies, storage has to be multi-functional and market-driven, rather than employed only in order to reduce imbalances resulting from wind energy.

In the Netherlands, several studies were devoted to cost-benefit analysis for large scale energy storage systems (Ummels et al., 2008; de Boer et al., 2007). In particular an energy storage system has been proposed that would provide the following functions (de Boer et al, 2007):

- Download capacity for wind power at night during high wind and light load periods;
- Download capacity at night for base-load units that cannot be switched off, coupled with additional production capacity during peak load;
- Extra production capacity during periods with cooling water discharge restrictions for conventional plants; and
- Primary action.

Section 7.4 describes the benefits of such a system when it is used to perform the first function.

3.2.4 Wind farm control

Although in a technical sense clustering of wind farms into a virtual power plant may provide benefits for active power management and reactive power control, it is not economically attractive to operate such a plant for power balancing if the market design penalizes curtailment, as shown in Germany (Wolff et al., 2006). However, occasional use of wind farms to provide downward regulating power may be attractive during certain periods, e.g. when the surplus price is negative.

3.3 Balancing market design

As to the market design for balancing services, there are major differences between various countries (Verhaegen et al., 2006), where each market design has an unique impact on how balancing is actually provided. For example, there are differences in the institutional environment where the responsibility for taking care of imbalances arising from wind power either is assigned to a system operator (Germany, Spain, and Denmark for onshore wind power) or to a market party (the Netherlands, United Kingdom and Denmark for offshore wind power). Also, differences exist in the rules of use and provision of balancing services. In the following a number of developments are listed.

In the past years progress has been made to increase the liquidity of intra-day markets. Gate closure times of about one hour ahead of delivery (such as in the Netherlands) are sufficient to increase the accuracy of wind energy predictions to an acceptable level. This is in addition to the single-buyer balancing market, which is operated by the Transmission System Operator (TSO).

Power systems with dual imbalance pricing are problematic for wind energy due to the high penalties imposed, e.g. in the United Kingdom. To minimize imbalance costs, market parties should aggregate their production portfolios (Gibescu et al., 2008a).

If market parties employ wind power forecasts without being made responsible for balancing, their aim would be to optimize financial gains rather than to minimize their imbalance. This is why in such cases aggregated wind power forecasts have to be managed by the TSO.

There is a clear trend in Europe towards more cross-border balancing, which certainly promises advantages for wind power (Verhaegen et al., 2006). Balancing geographically larger control areas will provide benefits for wind power, not only because of overall decreased variability and increased predictability, but also because of larger market volumes and larger balancing resources.

Finally it is noted that in all European countries the present organization of support schemes – which to date remains the major source of revenues for wind power producers – discourages the use of curtailment as a balancing instrument. Controlling the power output of wind farms must therefore be considered as an option from a power system operations perspective, since the opportunity loss by curtailment is significant.

4. Wind modeling aspects of wind energy integration

4.1 Outline

This section presents the modeling of wind variability and wind predictability and its relevance to wind energy integration. First, section 4.2 critically reviews existing methods to generate wind power time series for integration studies. Next, the sections 4.3 and 4.4 present a new method to create measured respectively forecasted wind speed time series. And finally in section 4.5 the method to create wind power time series is explained. The

methods described in the sections 4.3-4.5 were developed for this purpose by the authors (Brand, 2006; Gibescu et al., 2006; Gibescu et al., 2009).

4.2 Existing methods

A wind power integration study requires wind power time series originating from wind speed time series, where wind speed comprises measured and forecasted data. In addition the spatial correlation of wind speeds between sites must be taken into account because, as wind farms will be concentrated in areas with favorable wind conditions, their outputs will be strongly correlated. The resulting cross-correlations are essential when assessing the system-wide variability and predictability in large-scale wind production, and in turn affect the system requirements for reserve and regulation energy.

Three different methods to generate wind time series can be identified, namely by using actually measured wind speed time series, by using synthesized wind time series data (Doherty & O'Malley, 2005), or by using a combination of measured and synthesized wind speed time series (Giebel, 2000; Holttinen, 2005; Norgard et al., 2004). Valued against the requirements for integration studies these methods fall short for the creation of *both* realistic measured and forecasted wind power time series.

In order to correctly account for the spatial and temporal correlations of wind in an area, the method in section 4.3 derives the relevant statistical properties of the interpolated series from measured wind speeds. To this end assumptions are made only regarding the Markov property and the exponential decay of covariance with distance. In addition, this method uses 15-minute averaged wind speed in order to accurately model the balancing market in the Netherlands.

Two methods to generate wind forecasts can be identified, namely by using real wind forecasts (Lange & Focken, 2005) or by using synthesized wind forecasts (Norgard et al., 2004; Söder, 2004).

In order to correctly account for the limitations in a forecasting method and for the degree of uncertainty, in section 4.4 real wind forecasts are used. Unlike the alternative, this approach does not require assumptions on the distribution, correlation and increase of wind speed forecasting errors.

4.3 Measured wind speed

4.3.1 Historical wind data

Wind speed was modeled using historical wind data. To this end wind speed data sets were obtained from the Royal Dutch Meteorological Institute (KNMI). The data comprise 10-minute wind speed averages with a resolution of 0.1 m/s for 16 locations in the Netherlands and its coastal waters (six onshore, four coastal and six offshore; see figure 1) measured between 31 May 2004 and 1 June 2005. In addition, 10-minute wind speed standard deviations are available for the onshore locations and are estimated for the offshore locations. (The standard deviations are used in the height transformation in section 4.3.2.) The chosen time series reflects the spatial distribution of present and future installed wind power in the Netherlands.

4.3.2 Height transformation

Sensor height where wind speed was measured may differ between locations. The standard method to transform to hub height is to employ the logarithmic vertical wind speed profile

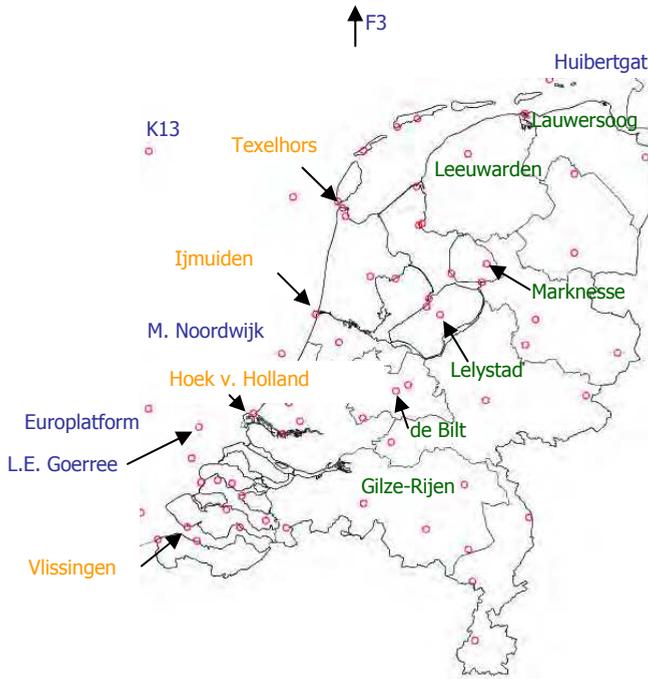


Fig. 1. Onshore, coastal and offshore wind speed measurement sites in this study

in combination with the surface roughness length (e.g. Walker & Jenkins, 1997). The local surface roughness length however is difficult to estimate. For this reason Brand, 2006, has eliminated this need. Instead, two location-dependent parameters are used: the friction velocity u^* and the average Monin–Obukhov length L_{esti} . The friction velocity is estimated from the 10-minute wind speed standard deviation which for most locations is available. If not, for an offshore location the friction velocity is estimated from the vertical wind speed profile. The Monin-Obukhov length is estimated by the average value that follows from the positive average heat flux that has been found over the North Sea and over the Netherlands, implying that the average vertical wind speed profile is stable (Brand & Hegberg, 2004). Given the 10-minute average wind speed $\mu(z_s)$ and standard deviation $\sigma(z_s)$ at sensor height z_s , the estimates of the wind speed average and standard deviation at hub height z_h are:

$$\mu_{u,esti}(z_h) = \mu_u(z_s) + \sigma_u(z_s) \left(\ln\left(\frac{z_h}{z_s}\right) + 5 \frac{z_h - z_s}{L_{esti}} \right) \tag{1}$$

and

$$\sigma_{u,esti}(z_h) = \sigma_u(z_s), \tag{2}$$

where L_{esti} is the location-dependent average Monin-Obukhov length.

If only $\mu(z_s)$ is available, and provided that the location is offshore, the estimates of the wind speed average and standard deviation at hub height are

$$\mu_{u,esti}(z_h) = \mu_u(z_s) + 2.5u_* \left(\ln \left(\frac{z_h}{z_s} \right) + 5 \frac{z_h - z_s}{L_{esti}} \right) \quad (3)$$

and

$$\sigma_{u,esti}(z_h) = 2.5u_*; \quad (4)$$

where u_* is determined from

$$\mu_u(z_s) - 2.5u_* \left(\ln \left(\frac{z_s g}{A u_*^2} \right) + 5 \frac{z_s}{L_{esti}} \right) = 0, \quad (5)$$

and $g = 9.81 \text{ m/s}^2$ is the gravitational acceleration and $A = 0.011$ is Charnock's constant.

4.3.3 Averaging-time transformation

A transformation from 10 to 15-minute averages is required by the design of the Dutch balancing market and is accomplished as follows: If $\mu_k, \mu_{k+1}, \mu_{k+2}$ etc are the consecutive 10-minute wind speed averages, then m_k, m_{k+1} etc. are the consecutive 15-minute wind speed averages:

$$m_{k,esti} = \frac{2\mu_{3(k-1)/2+1} + \mu_{3(k-1)/2+2}}{3} \quad \text{and} \quad m_{k+1,esti} = \frac{\mu_{3(k-1)/2+2} + 2\mu_{3(k-1)/2+3}}{3}.$$

4.3.4 Interpolation

4.3.4a Introduction

This section describes how wind speed at given locations is sampled conditionally on the wind speed at measurement locations. To this end a multivariate Gaussian model is used, in combination with assumptions on the spatial and the temporal covariance structure. In addition, a variance-stabilizing transformation is used.

4.3.4b Approach and assumptions

Consider the natural logarithm $W(x, t)$ of the wind speed at a location x and time t , where $t = (d, k)$ is defined by the day of the year d and the time of day k . There are two reasons for taking the logarithm. First, there is a pronounced heteroscedasticity (i.e. increasing variance with the mean) in the wind speeds, which is stabilized by the log transformation (section 9.2 in Brockwell and Davis, 1991). Second, upon taking logarithms the (multivariate) normal case is reached, which allows one to make extensive use of conditioning.

Following Brockwell and Davis, 1991, a random vector \underline{X} is considered which is distributed according to a multivariate normal distribution with mean vector $\underline{\mu}$ and covariance matrix $\underline{\Sigma}$. Supposing that \underline{X} is partitioned into two sub-vectors, where one corresponds to the sampled data and the other to the observed data, and, correspondingly, the mean vector and covariance matrix, then the following may be written:

$$\underline{X} = \begin{pmatrix} \underline{X}^{(1)} \\ \underline{X}^{(2)} \end{pmatrix} \quad \text{and} \quad \underline{\mu} = \begin{pmatrix} \underline{\mu}^{(1)} \\ \underline{\mu}^{(2)} \end{pmatrix} \quad \text{with} \quad \underline{\Sigma} = \begin{pmatrix} \underline{\Sigma}_{11} & \underline{\Sigma}_{12} \\ \underline{\Sigma}_{21} & \underline{\Sigma}_{22} \end{pmatrix}. \quad (6)$$

If $\det(\Sigma_{22}) > 0$, then the conditional distribution of $\underline{X}^{(1)}$ given $\underline{X}^{(2)}$ is again multivariate normal, and the conditional mean and the conditional covariance matrix are:

$$\underline{\mu}^{(1)} + \Sigma_{12} \Sigma_{22}^{-1} (\underline{X}^{(2)} - \underline{\mu}^{(2)}) \quad \text{and} \quad \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}. \tag{7}$$

As to the log wind speeds $W(x, t)$ at location x and time $t = (d, k)$, the following model is proposed:

$$W(x, t) = \mu(x, k) + \varepsilon(x, t), \tag{8}$$

where μ is a deterministic function representing the daily wind pattern by location and ε is a zero-mean random process representing the variations around the mean. Note that it has been assumed that μ depends on time only through the time of day k . In other words, the model does not include seasonal effects. (This assumption was checked and found to be reasonable in an analysis aimed at finding any other trend or periodic component, in particular a seasonal, in the 1-year data set.)

Figure 2 shows the average daily wind pattern for the 16 measurement locations. Since the lower curves correspond to onshore and the higher curves to offshore sites, the figure suggests that a daily effect is modeled which varies smoothly with geographical location. An onshore site is found to have a typical pattern with a maximum around midday, whereas an offshore site has a much flatter daily pattern, with a higher overall average. A coastal site falls in between.

The mean log wind speed $\mu(x, k)$ is estimated at all measurement locations by the daily averages shown in figure 2. Estimates for the locations of interest within the convex hull formed by the measurement sites were obtained by using linear spatial interpolation. On the other hand, for locations outside that hull, nearest neighbor interpolation was used. The results are shown as dotted lines in figure 2.

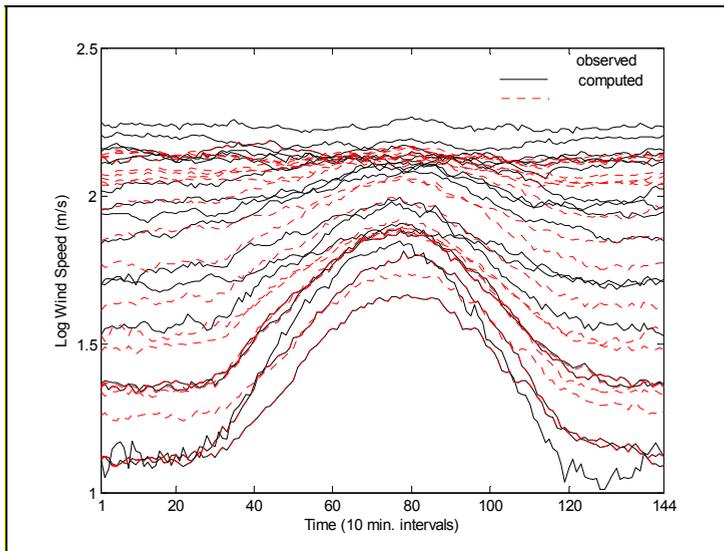


Fig. 2. Daily wind speed pattern for measured and interpolated sites

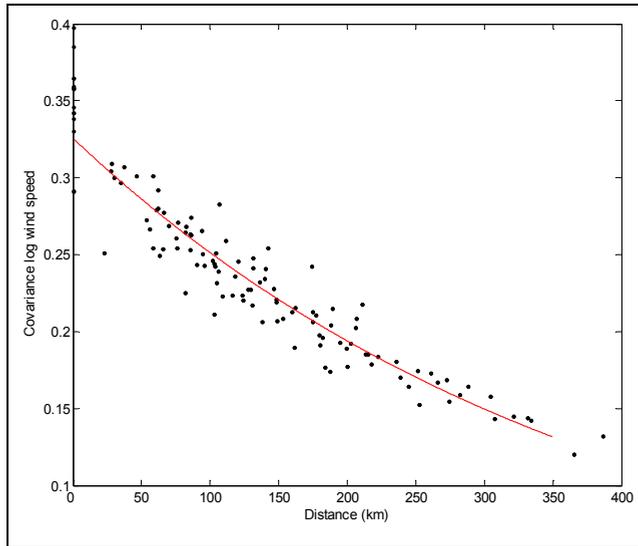


Fig. 3. Wind speed covariance versus site distance for 16 measurement sites

As to the model for the random part $\varepsilon(x, t)$, as explained above, a zero-mean, multivariate normal distribution is assumed for the log wind speeds minus the daily pattern. Figure 3 shows the sample covariance between the log wind speeds at all pairs of (measurement) locations versus the distance between them. From the displayed decay and the assumption that covariance vanishes at very large distances, it is reasonable to propose an exponential decay with distance:

$$\text{Cov}\left(\varepsilon\left(x_i, t\right), \varepsilon\left(x_j, t\right)\right) = \alpha_0 \exp\left(-\beta\left\|x_i - x_j\right\|\right) \tag{9}$$

where $\|\cdot\|$ denotes the Euclidean distance. To be able to sample wind speed time series, temporal dependence must be taken into account. Similar to equation (9), the following covariance is proposed:

$$\text{Cov}\left(\varepsilon\left(x_i, t\right), \varepsilon\left(x_j, t-1\right)\right) = \alpha_1 \exp\left(-\beta\left\|x_i - x_j\right\|\right) \tag{10}$$

The parameters α_0 , α_1 and β are jointly estimated by a least squares fit. The fit for α_0 and β is shown in figure 3, where $\alpha = 0.32$ and $1/\beta = 392.36$ km. The latter term is known as the characteristic distance. By transforming the parameters of this decay fit from logarithmic to pure wind speeds, and by inspecting the correlation coefficients (i.e. covariance normalized by the product of the two standard deviations) between location pairs, a value of 610 km is obtained for the characteristic distance. This value is in line with the 723 km reported in Chapter 6 of Giebel, 2000, which is based on measurements from 60 locations spread throughout the European Union, and the 500 km reported in Landberg et al., 1997, and Holttinen, 2005, using Danish only and Scandinavian data, respectively. This suggests that these values are generic.

A final assumption is the Markov property for the sampled time series: it is assumed that conditionally on $W(x,t-1)$, $W(x,t)$ does not depend on $W(x,t-2)$, $W(x,t-3)$, etc. Consequently, it is not needed to specify the covariance between $W(x_i,t)$ and $W(x_j,s)$ when $s-t > 1$.

It should be noted that since the equations 9 and 10 do not depend on time, any daily or seasonal changes in the covariance structure are ignored. Such effects have been tried to identify, but it was found that they were not very large, and not particularly systematic; hence, they would not have a substantial effect on the time series that the method ultimately generates.

4.3.4c Interpolation scheme

The interpolation scheme is as follows. At each stage, a collection of normal random variables is conditionally sampled on some other normal random variables. The mean and the covariance structure of all random variables is fully described, and therefore the general theory from equations 6 can be used, where subset (1) denotes the unobserved wind speeds at time t , and subset (2) denotes both observed wind speeds at times t and $t-1$, and unobserved, but already interpolated values at time $t-1$.

Once the log wind speeds for the locations of interest are sampled, these are exponentiated to obtain the wind speeds. Of course, the time series produced in this way will reflect the assumptions that were made, but this does not mean that they will look like samples from the multivariate log-normal distribution. The method provides nothing more than linear interpolations of the measured time series, and so their Weibull character will be preserved to a great extent.

The effectiveness of the method is evaluated by using cross-validation: leaving one measurement location out of the data set and using the remaining $n-1$ locations to "re-create" it. First, it is verified that the method preserves the marginal Weibull parameters. As an illustration, figure 4 shows the histogram of the original data for the coastal location IJmuiden together with a Weibull fit of the original and the interpolated data. As expected, some smoothing has occurred in the interpolated data due to the weighted averaging, but not much. Second, it is verified whether or not the method reproduces the (auto-)covariance structure of the original data. Figure 5 shows the lag-one auto-correlations for the original and cross-validated data, with the straight line indicating a perfect match. Even though some over- and underestimation of the auto-covariances can be observed from figure 5, there does not seem to be any structural bias.

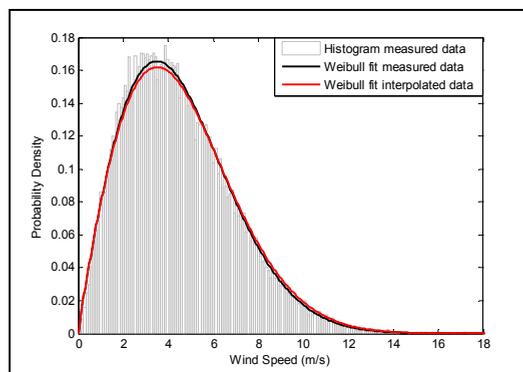


Fig. 4. Wind speed histogram and fit to Weibull distribution at the location IJmuiden

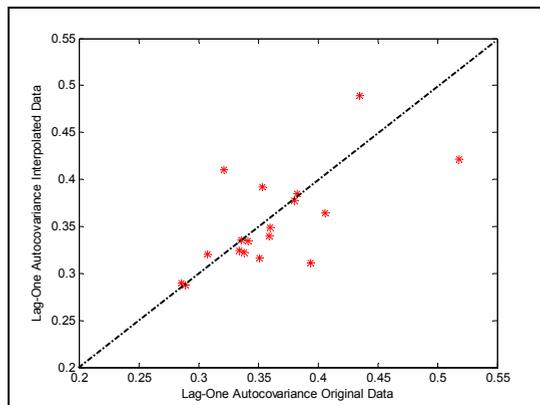


Fig. 5. Lag-one auto-covariance, original versus interpolated wind speeds

As to limitations of this method, it should be kept in mind that the interpolation weights are determined by the assumption of the exponential decay of the covariance with distance. As a consequence, if this decay does not hold, the covariance structure of the generated series will not be correct. In addition, the estimated time series are only as good as the input data allows. For instance, under more complex terrain, measured data at closer distances would be required to correctly track local changes in wind behavior.

4.4 Forecasted wind speed

The 15-minute average wind speed forecast time series are generated for locations where measurements are available. These forecasts originate from the wind power forecasting method AVDE (Brand and Kok, 2003); a physical forecasting method with an output statistics module. In an operational sense, AVDE is a post-processor to the high-resolution atmospheric model HiRLAM or any weather prediction model that delivers the required input data (two horizontal wind speed components, temperature and pressure in two vertical levels on a horizontal grid covering the sites to be considered) in the required format (GRIB). If wind speed and/or wind power realizations are available, the output statistics module of the AVDE can be used in order to compensate for systematic errors in the forecasts. The forecasts are meant to guide wind producers in a day-ahead market, and are completed at 12:00 the previous day, thus carrying an increasing delay of 12 to 36 hours. By employing a method similar to the one used for the spatial interpolation of wind speed measurements, appropriately correlated forecast error time series are generated for the wind farm locations. Since the variability of wind forecast errors over successive time intervals is not analyzed, it is assumed that, conditional on the forecast errors at the observed locations, the forecast errors at the computed locations at time t are independent of the errors experienced at time $t-1$.

Figure 6 presents the geographical locations of the seven wind speed forecast sites together with the projected offshore wind farm locations for the year 2020 and the current density of onshore wind energy capacity by province in the Netherlands.

Similar to the wind speeds, the forecast errors are modeled as the sum between a deterministic term, derived from the average daily pattern (figure 7), and a random term, which obeys a covariance matrix derived from the exponential fit presented in figure 8. Note

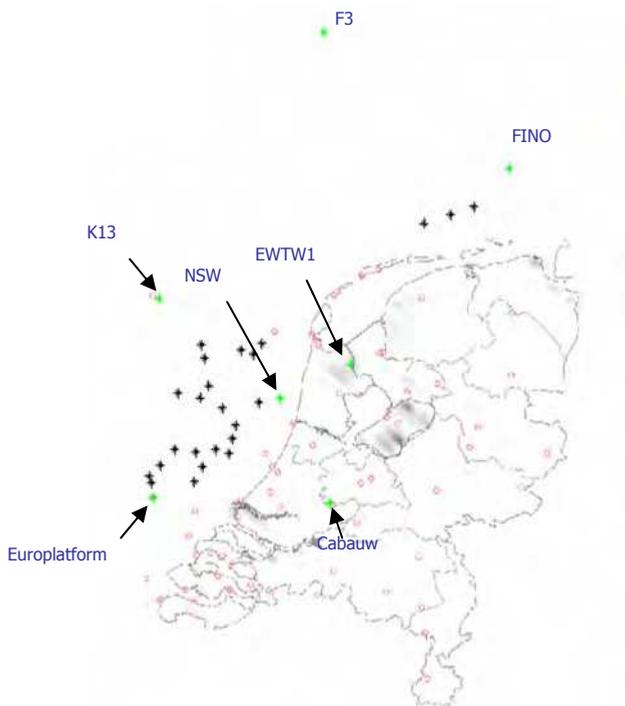


Fig. 6. Wind speed forecast sites (labeled), onshore (shaded grey) and offshore (black stars) wind farm sites for the Basic 2020 scenario

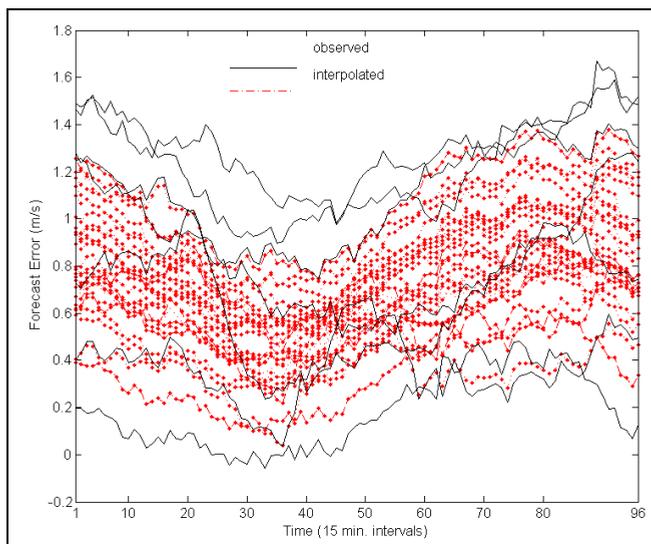


Fig. 7. Daily wind speed forecast error pattern for measured and interpolated sites

that the logarithmic transformation was not necessary here because the variance of the forecasting error does not significantly increase with its mean. In order to correctly take into account the changes in the covariance structure due to the look-ahead time, $24 \times 4 = 96$ separate exponential decay curves were fitted as shown in figure 8.

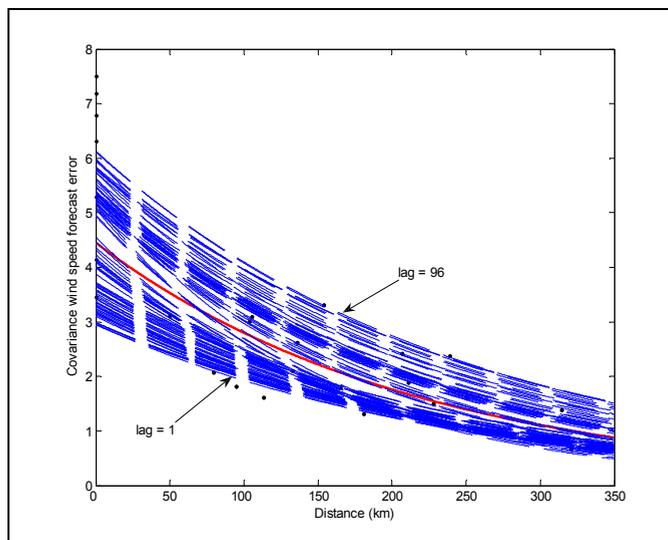


Fig. 8. Wind speed forecast error covariance versus distance for various forecast horizons

4.5 Wind power

4.5.1 Multi-turbine power curve

For each location wind power has been created using regionally averaged power curves, which depend on the area covered with wind turbines and the standard deviation of the wind speed distribution at the location. As the name suggests, regional averaging provides the average power of a set of wind turbines placed in an area where the wind climate is known, assuming the turbines do not affect each other. The multi-turbine curve is created by applying a Gaussian filter to a single-turbine power curve, and is not to be confused with a wind farm power curve, which brings the wind shadow of turbines into account.

Although inspired by and having the same effect as the Gaussian filter in the multi-turbine approach of Norgard and Holttinen, 2004, the standard deviation in the new filter correctly originates from the local wind climate alone. Unlike the Norgard-Holttinen method, the filter does not require estimating the turbulence intensity, which incidentally is a measure of variation in a 10-minute period in a given location rather than a measure of variation in the same 10-minute period at different locations. Nor does the method apply a moving block average to the wind speed time series with the time slot arbitrarily based on the local average wind speed.

Figure 9 shows an example of a multi-turbine power curve as constructed for an offshore wind farm of installed power 405 MW at a location where the standard deviation of the wind speed is 4.6 m/s. The width σ_F of the Gaussian filter is given by an estimate for the standard deviation that describes the regional variation of wind speeds at different locations in the same wind climate (appendix A in Gibescu et al., 2009)

$$\sigma_F = \sigma \sqrt{\frac{1}{2} \left(1 - \exp \left(-\frac{d_{ave}}{D_{decay}} \right) \right)}, \tag{12}$$

where σ is the standard deviation of the wind speed distribution, d_{ave} is the average distance between the locations and D_{decay} is the characteristic distance of the decay of correlation (as estimated in section 3). If the individual locations are not known, as is the case in this study, an estimate for d_{ave} is (appendix B in Gibescu et al., 2009):

$$d_{ave} = \frac{2}{3} \sqrt{\frac{A}{\pi} \left(1 + \frac{2}{\sqrt{M}} \right)}, \tag{13}$$

where A is the area of the region and M is the number of locations in that area. In this study, the area relates to a province for the onshore wind power and to an individual wind farm for the offshore wind power. The area of an individual farm is approximated by the area of a rectangle whose sides depend on the number of turbines, the rotor diameter and the spacing between turbines.

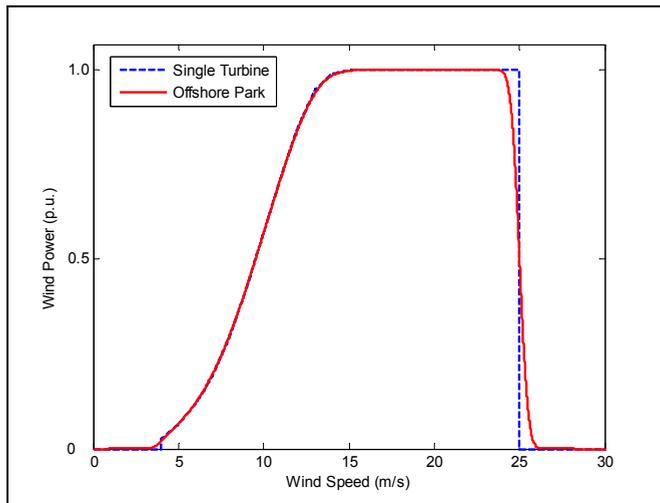


Fig. 9. Example of an aggregated power curve

The method to determine the regional variation of wind speeds at different locations in the same wind climate was verified by using the measured data introduced in section 4.3. The method to determine the multi-turbine power curve for a given area is still in need of verification data.

4.5.2 Aggregation levels

Aggregating the power of the individual wind farms at the system level gives a good initial estimate for the degree of variability and predictability that come with large-scale wind energy. It however ignores the real situation where wind power is integrated by several sub-levels, as owned and operated by the individual market parties. To that effect, seven PRPs

are defined, each owning a unique combination of installed power and geographical spread of onshore and offshore wind farms, as described in table 3. For reasons of confidentiality, these parties have fictitious names; however, the installed power are consistent with the current and planned developments in the Netherlands.

PRP	Offshore (MW)	Onshore (MW)	Total (MW)
Anton	881	840	1721
Berta	1792	593	2385
Cesar	800	0	800
Dora	2520	140	2660
Emil	40	0	40
Friedrich	0	92	92
Gustav	0	135	135
System	6033	1800	7833

Table 3. Programme Responsible Parties (PRP) in the Basic 2020 scenario

5. Impact of extra variability due to wind

In this section the balancing energy requirements due to wind variability are presented for the scenario with 7.8 GW of installed wind power in the Netherlands in the year 2020.

Given the locations and installed power for future wind farms, the estimation method of the sections 4.3 and 4.4 is used in combination with the aggregated power curve of section 4.5 to compute the average wind power generated per 15-minute time interval for the duration of a year. By differentiating the wind power time series an estimate is obtained of the variability of aggregated power across 15-minute time intervals and above. This quantity and its sign are of interest because simultaneous load and wind variations are to be balanced by the remaining conventional generation units via the up- or down-ramping of their outputs.

Table 4 presents the 99.7% confidence intervals and the extreme values (smallest and largest) of the 15-minute, 30-minute, 1-hour and 6-hour variations at the system level. The sorted positive and negative variations in wind power over various time ranges are shown in figure 10. Based on the 99.7% confidence interval, the system-wide variations across 15-minute intervals are in the range of $\pm 14\%$ of the installed power for this scenario.

Table 5 shows the statistics of the 15-minute variations for each of the seven PRPs individually. These variations are in the range of $\pm 12\text{--}26\%$ of the power installed by the PRP, depending on the geographical spread of its locations. The collective requirement for balancing 15-minute variations becomes approximately $\pm 16\%$ of the system's installed capacity, which is 2% more than the requirement at the system level.

Time range	Minimum (MW)	Maximum (MW)	99.7% Conf.Int. (MW)
15 min	-2411	2883	-1090.8 to 1054.2
30 min	-2411	2883	-1252.9 to 1309.6
1 hour	-3133	3634	-1968.0 to 1846.0
6 hour	-7211	6790	-5157.8 to 5105.4

Table 4. Statistics of wind variability in the Basic 2020 scenario

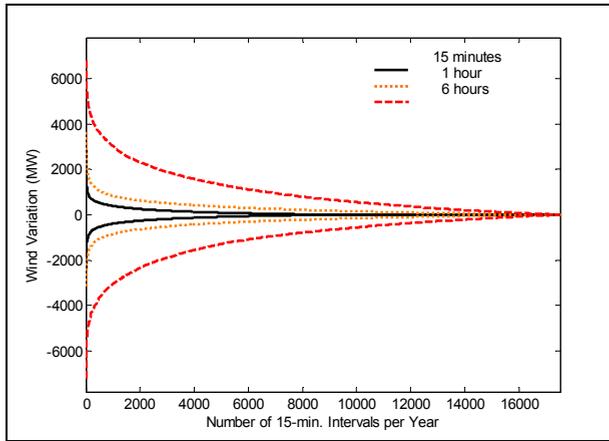


Fig. 10. Variations in 7830 MW aggregated wind power

PRP	Minimum (MW)	Maximum (MW)	99.7%Conf.Int. (MW)
Anton	-367	481	-201 to 197
Berta	-755	825	-323 to 327
Cesar	-482	448	-191 to 188
Dora	-1264	1420	-461 to 484
Emil	-36	38	-9 to 9
Friedrich	-48	42	-22 to 24
Gustav	-74	78	-26 to 27
Total PRPs	-3026	3332	-1233 to 1256
System	-2411	2883	-1091 to 1054

Table 5. Statistics of 15-minute variability at the PRP level

6. Impact of limited wind predictability

In this section balancing energy requirements due to the limited predictability of wind are presented for the scenario with 7.8 GW of installed wind power in the Netherlands in the year 2020.

To this end a statistical analysis is performed of the forecasting error as aggregated over the wind production of the Netherlands. The time series of forecasted 15-minute average wind power include different day-ahead forecasts issued at 24, 18, 12 and 6 hours before delivery. System reserve is allocated among online generators to account for equipment outages and uncertainties in load and wind forecast errors. Obviously the higher the forecast uncertainty, the larger the amount of reserve needed to achieve the same reliability level. Figure 11 shows the normalized histogram for the system-aggregated forecast error, together with the fit to a double-exponential probability density function, which was found to be a more accurate analytical representation of the data than the normal distribution.

Table 6 shows the predictability at the system level in terms of the 99.7% confidence interval plus the average, standard deviation, minimum and maximum of the imbalance. (Imbalance

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